

ON THE RELATION BETWEEN SCHWARZSCHILD'S AND KERR'S MANIFOLDS

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ABSTRACT. Kerr's manifold is only a Schwarzschild's manifold as "seen" by a suitably rotating coordinate system. By taking into account this fact, Kerr's manifold can be "reduced" to a Schwarzschild's manifold. – In a final *aperçu* we summarize the main steps of our reasoning.

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1. – The standard (Hilbert-Droste-Weyl) form for the ds^2 of Schwarzschild's manifold of a gravitating point mass m is – if r' , ϑ' , φ' are spherical polar coordinates:

$$(1) \quad \begin{aligned} ds^2 = & \left(1 - \frac{2m}{r'}\right)^{-1} dr'^2 + r'^2 (d\vartheta'^2 + \sin^2 \vartheta' d\varphi'^2) - \\ & - \left(1 - \frac{2m}{r'}\right) dt'^2 \quad ; \quad (G = c = 1) \quad . \end{aligned}$$

With Boyer and Lindquist (see [1], [2]), the ds^2 of Kerr's manifold can be written as follows:

$$(2) \quad \begin{aligned} ds^2 = & \left(\frac{dr^2}{\Delta} + d\vartheta^2\right) \Sigma + (r^2 + a^2) \sin^2 \vartheta d\varphi^2 - dt^2 + \\ & + \frac{2mr}{\Sigma} (a \sin^2 \vartheta d\varphi + dt)^2 \quad ; \quad (G = c = 1) \quad , \end{aligned}$$

where: $\Sigma \equiv r^2 + a^2 \cos^2 \vartheta$; $\Delta \equiv r^2 - 2mr + a^2$. The parameter a has a geometrical and kinematical meaning. *The case $m \geq a$ is physically interesting.* When $a = 0$, eq. (2) coincides with eq. (1).

2. – The potential g_{jk} , ($j, k = 1, 2, 3, 4$), of eq. (2) is referred to a frame which rotates with the following angular velocity $g_{t\varphi}/g_{\varphi\varphi} \equiv \omega$:

$$(2') \quad \omega = \frac{2ma}{(r^2 + a^2)(r^2 + a^2 \cos^2 \vartheta) + 2ma^2 r \sin^2 \vartheta} \quad ;$$

at $r = 0$, we have $\omega = 0$: this means, strictly speaking, that the gravitating point mass does *not* rotate. For $r \neq 0$ and $m \neq 0$, ω is equal to

zero if and only if the parameter a is equal to zero, and in this case Kerr's manifold coincides with Schwarzschild's manifold, as we have seen in sect.1.
 – Of course, an $\omega \neq 0$ generates *dragging* forces.

3. – Kerr's surface $r = m + (m^2 - a^2 \cos^2 \vartheta)^{1/2}$, which is tangent to the surface $r = m + (m^2 - a^2)^{1/2}$ at $\vartheta = 0$ and $\vartheta = \pi$, has this property: if we make in eq. (2) the coordinate shift (a legitimate choice of a new radial coordinate):

$$(3) \quad r \rightarrow r + m + (m^2 - a^2 \cos^2 \vartheta)^{1/2} \quad ,$$

we obtain a $\Delta \geq 0$; the equality holds for $r = 0$ and $\cos^2 \vartheta = 1$. Indeed, the new Δ is:

$$(4) \quad \begin{aligned} \Delta &= \left[r + (m^2 - a^2 \cos^2 \vartheta)^{1/2} - (m^2 - a^2)^{1/2} \right] \cdot \\ &\cdot \left[r + (m^2 - a^2 \cos^2 \vartheta)^{1/2} + (m^2 - a^2)^{1/2} \right] \geq 0 \quad ; \end{aligned}$$

and if $\cos^2 \vartheta = 1$:

$$(4') \quad \Delta_{\vartheta=0,\pi} = r \cdot \left[r + 2(m^2 - a^2)^{1/2} \right] \quad .$$

When $a = 0$, transformation (3) becomes:

$$(3') \quad r \rightarrow r + 2m \quad ,$$

which coincides with Brillouin (-Schwarzschild) transformation of radial coordinate r' of eq. (1) [3].

Brillouin's form of Schwarzschildian ds^2 and the above new form of Kerr's ds^2 have *both* a **sole** (and “soft”) singularity at $r' = r = 0$. This means that eq. (1) and eq. (2) have a physical (and mathematical) meaning only when $r' > 2m$ and $r > m + (m^2 - a^2 \cos^2 \vartheta)^{1/2}$, respectively. Our paper quoted in [2] gives a striking proof of this assertion. (Accordingly, there is no room for the physical existence of BH's). – Remark that the new form (*à la* Brillouin) of Kerr's metric is **diffeomorphic** to the *exterior* part (*i.e.*, for $r > m + (m^2 - a^2 \cos^2 \vartheta)^{1/2}$) of the form of eq. (2), and is *maximally extended*. All the *observational* results concern only the exterior part of eq. (2), or equivalently the $r > 0$ region of the new form of ds^2 .

4. – We have seen that the singular surfaces $r' = 2m$ and $r = m + (m^2 - a^2 \cos^2 \vartheta)^{1/2}$ are in a strict correspondence. Moreover, we prove that this *Kerr's singular surface can be transformed into the surface $r' = 2m$ with an appropriate change of general coordinates*.

From the standpoint of a three-dimensional Euclidean *Bildraum*, a “vertical” section of the surface $r = m + (m^2 - a^2)^{1/2}$ is an ellipse (see Appendix);

accordingly, this surface is a rotational ellipsoid, i.e. an oblate spheroid. And the surface $r' = 2m$ is a sphere.

The semi-axes, say α and β , of the above ellipse are:

$$(5) \quad \begin{cases} \alpha = 2m & ; & \beta = m + (m^2 - a^2)^{1/2} & ; & \Rightarrow \\ \alpha^2 - \beta^2 = a^2 + 2m [m - (m^2 - a^2)^{1/2}] & . \end{cases}$$

We remark that

$$(6) \quad \{a = 0\} \Leftrightarrow \{\gamma^2 \equiv \alpha^2 - \beta^2 = 0\} \quad .$$

Obviously, if ξ, η are Cartesian orthogonal coordinates, the equation of our ellipse can be also written as follows:

$$(7) \quad \frac{\xi^2}{\alpha^2} + \frac{\eta^2}{\beta^2} = 1 \quad .$$

If $\xi = \xi', \eta = (\beta/\alpha) \eta'$, we have

$$(8) \quad \xi'^2 + \eta'^2 = (2m)^2 \quad ,$$

where:

$$(9) \quad \frac{\beta^2}{\alpha^2} = \frac{2m [m + (m^2 - a^2)^{1/2}] - a^2}{4m^2} \quad .$$

The transformation of the spheroid $r = m + (m^2 - a^2 \cos^2 \vartheta)^{1/2}$ into the sphere $r' = 2m$ is an immediate consequence of eq. (8).

This result has been obtained with a simple application of the following theorem of projective geometry: if we have an ellipsoid (resp. an ellipse) and a sphere (resp. a circle), there exist *collineations* that transform the ellipsoid (resp. the ellipse) into the sphere (resp. the circle).

The parameter a (its geometrical meaning is explained by eq. (6)), which is responsible for the spinning of Kerr's frame, has been "incorporated" in new coordinates; this implies that Kerr's manifold is *not* substantially distinct from Schwarzschild's manifold, because *the "soft" singularities $r' = 2m$ and $r = m + (m^2 - a^2 \cos^2 \vartheta)^{1/2}$ - which represent projectively the **same** geometrical object - characterize completely these manifolds*. Indeed, in the shifted coordinates *à la* Brillouin (-Schwarzschild) both manifolds are solutions of Einstein equations $R_{jk} = 0$, ($j, k = 1, 2, 3, 4$), with *one and only* "soft" singularity at the origin of the radial coordinates ($r' = r = 0$); the surfaces $r = 2m$ and $r = m + (m^2 - a^2 \cos^2 \vartheta)^{1/2}$ are really *not* surfaces but *single points*.

5. - The above conclusion is similar to this Weyl's result [4]: the ds^2 of eq. (1) can be expressed also in a cylindrical system of coordinates (Weyl's "canonical" system) z^*, r^*, ϑ^* . Then, the "globe" $r' = 2m$ becomes the "segment" $-m \leq z^* \leq +m$.

Our case is a little more involved, owing to the presence of the parameter a , which however can be “taken up” by the coordinate change that allows the transformation of the spheroid $r = m + (m^2 - a^2 \cos^2 \vartheta)^{1/2}$ into the sphere $r' = 2m$.

When $m = 0$ and $a \neq 0$, there is a simple relation between $(r', \vartheta', \varphi', t')$ and $(r, \vartheta, \varphi, t)$, see Appendix of paper [2]; in this case, eq. (1) and eq. (2) give only two different forms of *Minkowski* interval ds_M^2 .

6. – A consideration on the role of the *Killing vectors* [5]. As it is well known, they yield an *invariant* description of the symmetry properties of a given manifold. However, it is necessary to distinguish the Riemann-Einstein manifolds generated by *extended* material distributions from the Riemann-Einstein manifolds generated by *punctual* masses, that are solutions of $R_{jk} = 0$ with a singularity at the origin of the coordinates. In this second case, we can have manifolds with *any* kind of symmetry: indeed, a mass point can be considered as a kind of limit of a material distribution of any symmetry – and therefore a coordinate system “adapted” to a chosen symmetry is also adequate to the field generated by the material point. In other terms, the manifold created by a mass point does *not* possess a definite symmetry *of its own*. In sect.5 we have mentioned an example given by Weyl [4]. Another example is Kerr’s manifold: as we have seen, Kerr’s oblate spheroid $r = m + (m^2 - a^2 \cos^2 \vartheta)^{1/2}$ can be transformed, with a simple collineation, into the sphere $r' = 2m$. In this way, *Kerr’s manifold is “reduced” to Schwarzschild’s manifold of a mass point at rest*. (N.B. – The use of a *Bildraum* for the proof of this “reduction” does not restrict the validity of our result).

The ds^2 of eq. (1) can be considered, *e.g.*, as the limit of the ds^2 of a homogeneous sphere of an incompressible fluid, whose radius goes to zero [6]. The ds^2 of eq. (2) can be considered, *e.g.*, as the limit of the ds^2 of the above contracting sphere as “viewed” by a frame which rotates with the angular velocity ω of eq. (2').

Summing up, the difference between Kerr’s manifold and Schwarzschild’s manifold is *only* a difference of reference systems: Kerr’s metric is described by a *rotating* frame, Schwarzschild’s metric by a *static* frame. In *both* cases the material agent is the *same*: a point mass.

7. – *Aperçu.* – *i)* If the angular velocity of rotation contained in Kerr’s metric is equal to zero, Kerr’s manifold coincides with Schwarzschild’s manifold created by a point mass at rest. – *ii)* The coordinate shift $r \rightarrow r + m + (m^2 - a^2 \cos^2 \vartheta)^{1/2}$ in Kerr’s metric gives an expression of the ds^2 with a *sole* (and “soft”) singularity at $r = 0$. – *iii)* The oblate spheroid $r = m + (m^2 - a^2 \cos^2 \vartheta)^{1/2}$ can be transformed into the sphere $r' = 2m$. – *iv)* The difference between Kerr’s metric and Schwarzschild’s metric rests *only* on the difference between the respective reference frames. Accordingly, Kerr’s metric can be “reduced” to Schwarzschild’s metric by virtue of result

iii). – v) Of course, Kerr's potential g_{jk} gives origin to a Thirring-Lense *dragging* effect. However, all dragging forces are *only* caused by the chosen reference frames, and therefore do not have an *invariant* character. – vi) All *observational* data are in accord with our analysis. –

APPENDIX

We give here the banal proof that the vertical section of Kerr's surface $r = m + (m^2 - a^2 \cos^2 \vartheta)^{1/2}$, where $0 \leq r < +\infty$ and $0 \leq \vartheta \leq \pi$, is an ellipse.

If α, β are the semi-axes of a generic ellipse, and χ , ($0 \leq \chi < 2\pi$), is Kepler's eccentric anomaly, our curve can be described by the following equations – as it is well known:

$$(A1) \quad \xi = \alpha \cos \chi \quad ; \quad \eta = \beta \sin \chi \quad ,$$

where ξ, η are Cartesian orthogonal coordinates. If $\varrho^2 = \xi^2 + \eta^2$, we have:

$$(A2) \quad \varrho = [\beta^2 - (\beta^2 - \alpha^2) \cos^2 \chi]^{1/2} \quad .$$

Now, the equation $r - m = (m^2 - a^2 \cos^2 \vartheta)^{1/2}$ can also represent the half (ϑ is a colatitude) of the vertical section of the above Kerr's surface. We see that:

$$(A3) \quad \varrho(\chi = 0) = \alpha \quad ; \quad \varrho(\chi = \pi/2) = \beta \quad ,$$

$$(A4) \quad r(\vartheta = \pi/2) = 2m \quad ; \quad r(\vartheta = 0) = m + (m^2 - a^2)^{1/2} \quad ,$$

Q.e.d.

Accordingly, by virtue of the axial symmetry of Kerr's ds^2 , the surface $r = m + (m^2 - a^2 \cos^2 \vartheta)^{1/2}$ is a rotational ellipsoid. –

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- [3] M. Brillouin, *Journ. Phys. Rad.*, **23** (1923) 43; for an English translation by S. Antoci, see: *arXiv:physics/0002009* (February 3rd, 2000). See also the Schwarzschildian reference therein, which inspired Brillouin's paper. – Remark that in the new radial coordinate (eq. (3)), at $r = 0$ the angular velocity ω is different from zero.

- [4] H. Weyl, *Ann. Physik*, **54** (1917) 117.
- [5] See, *e.g.* L.P. Eisenhart, *Continuous Groups of Transformations* (Dover Publ., New York) 1961, p.208 *sqq.*
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- [7] Cf., *e.g.* H. Weyl, *The Classical Groups - Their Invariants and their Representations*, (Princeton University Press, Princeton, NJ) 1946, p.112 *sqq.*; and G. Castelnuovo, *Lezioni di Geometria Analitica* (Albrighi, Segati e C., Milano, *etc.*) 1938, p.p. 494 and 540.

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